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Designing Dynamic Distributed Cooperative Human-Machine Systems

# PROJECT description

D3CoS aims to develop new and affordable methods, techniques and tools that support the industrial development process of Dynamic Distributed Cooperative Human-Machine Systems, allowing for an improved development process, reduced costs and time to market.

### RELEVANCE to call

D3CoS targets ASP8 human-centric design of embedded systems by:

- > Defining a common methodology for DCoS Development
- > Developing and studying models of multi-modal human-machine interaction
- > Developing and studying cross-domain reusable techniques, reference designs and design patterns for multi-modal input and output devices

Agents

Resources

### MARKET innovation

D3CoS results – NEW AND AFFORDABLE METHODS, TECHNIQUES, and TOOLS - will:

- > allow for early design evaluations of new systems
- > improved evaluation of safety aspects of distributed cooperative human-machine systems due to a model-based development approach
- > reduce effort /cost and time to market of innovative and ambitious distributed cooperative humanmachine systems
- > improve the quality of system design, development, and evaluation
- > increase productivity and competitiveness of European manufacturers

## TECHNICAL innovation

D3CoS goes beyond traditional assistance systems and addresses the whole cooperative system development process from a multi- agent perspective in order to tackle challenges posed by future cooperative traffic environments. The D3CoS project seeks technical excellence through:

- > Open experimental simulation platform interfacing models of cooperative human and machine agents
- > Support for reusability of successful designs and design patterns for intelligent multi-modal humanmachine interfaces
- > Support for reusability of designs and design patterns for (human) state inference and state adaptation
- > Architectures for cooperative systems with Embedded Systems
- > A common methodology to integrate the D3CoS methods, techniques and tools into an easy-to-use, reliable, valid tool chain for DCoS Development, for industrial application.





Dynamic Task

Dynamic Resource



PROJECT COORDINATOR
START

Jan-Patrick Osterloh
March 2011

INSTITUTION
DURATION

OFFIS
36 months

EMAIL
TOTAL INVESTMENT

osterloh@offis.de
€14.1 M

WEBSITE
PARTICIPATING ORGANISATIONS

WWW.d3cos.eu
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NUMBER OF COUNTRIES

